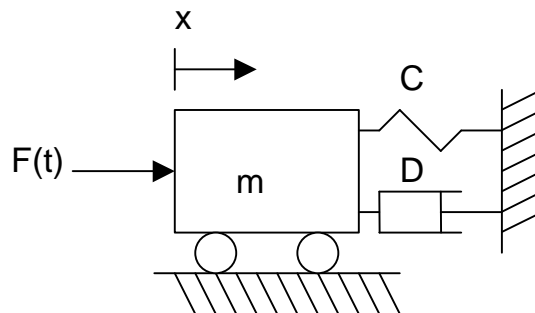


**Exercise 3:****Introduction to Simulink**

Simulink is a very powerful simulation environment. In this exercise some models are build up to learn the basic handling of Simulink that is:

- selection of model blocks from the libraries
- connection the model blocks
- change of the model parameters
- run the simulation and document the results.

- Explore the model libraries of Simulink. Special have a look on continuous, source and sink library. Which block do you already know?
- Simulate the step response of the transfer-function  $G(s) = \frac{4}{1+5s}$ : Display the result in a plot windows and export the results to the Matlab workspace. Repeat the simulation using different signal types of the signal generator of Simulink like sine, sawtooth, square and random.
- Build up the model of a one-mass spring system.



**Moving mass model**

$$m \cdot \ddot{x} = -C \cdot x - D \cdot \dot{x} + F(t) \text{ with}$$
$$m = 10 \text{ kg}; C=100 \text{ N/m}; D=3 \text{ N*sec/m};$$

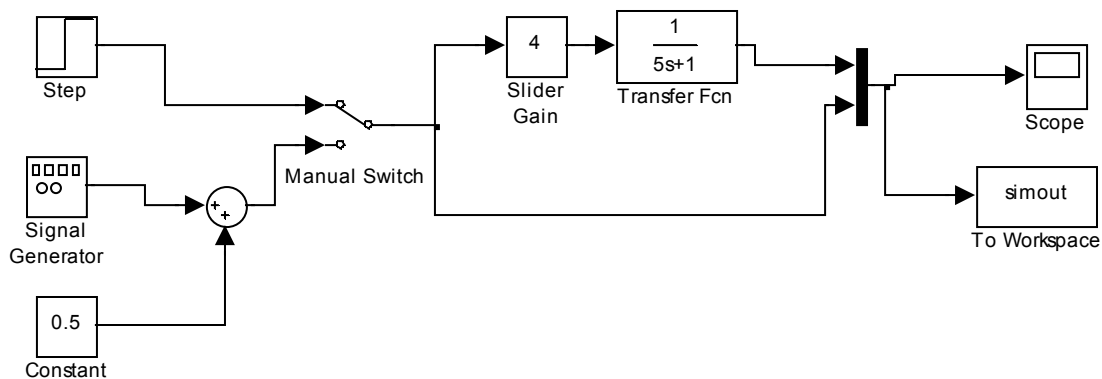
Calculate the step response and investigate the influence of the physical parameters on the simulation results!

Document and print your work using word.

### Exercise 3:

### Introduction to Simulink

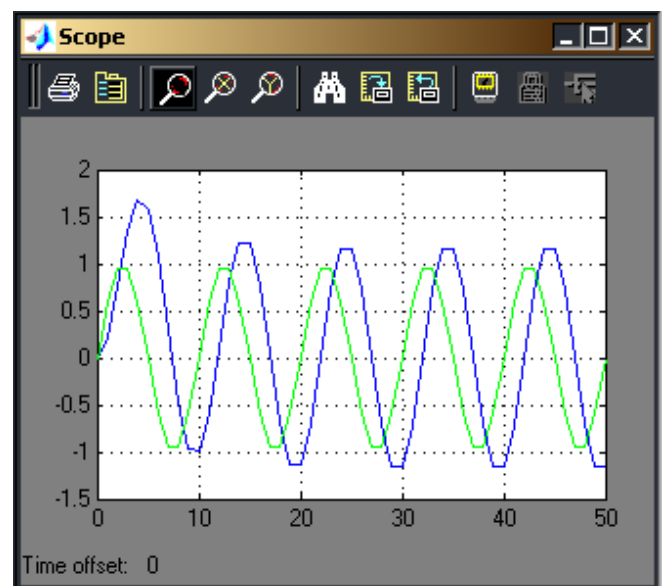
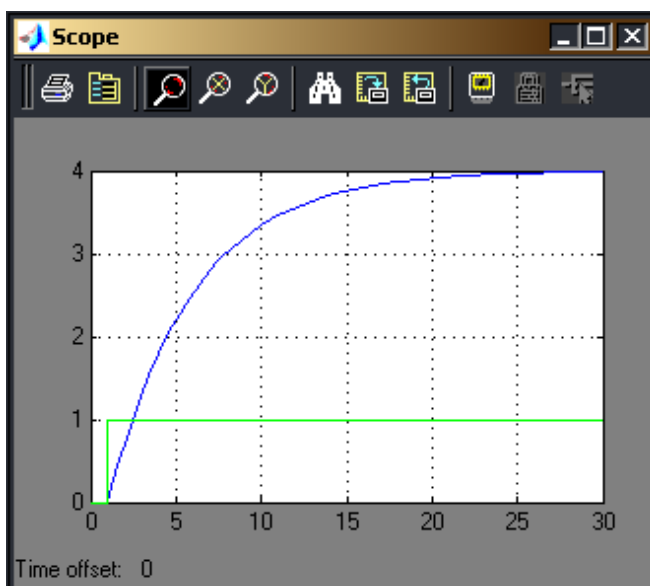
- Hilfreiches Werkzeug zum Auffinden von Blöcken ist Find im Library Browser.
- Erzeugtes Simulink Model zum experimentieren.



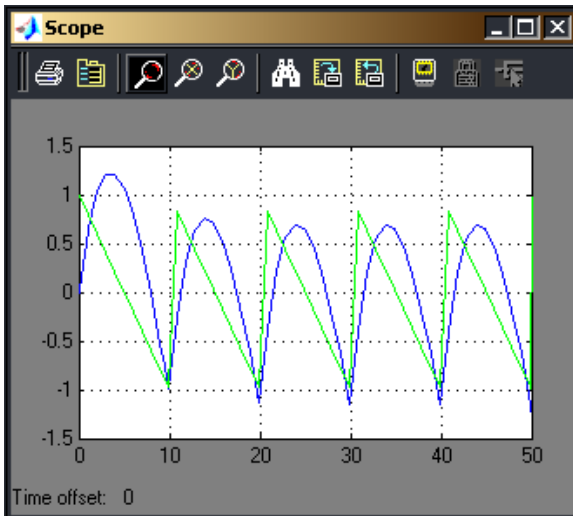
- Mit Hilfe des Manuel Switch lässt sich zwischen dem Signalgenerator und der Sprungfunktion umschalten.
- Werden die Simulationsdauer auf **inf** gesetzt, die Parameter des Scopes und des Signalgenerators aneinander angepasst, so kann mit dem Slider Gain die Verstärkung während der Simulation variiert werden.
- Export der Daten über simout block oder Scope (Data history). Es wird dabei eine Structure im Workspace mit den Werten erzeugt.

Sprungantwort:

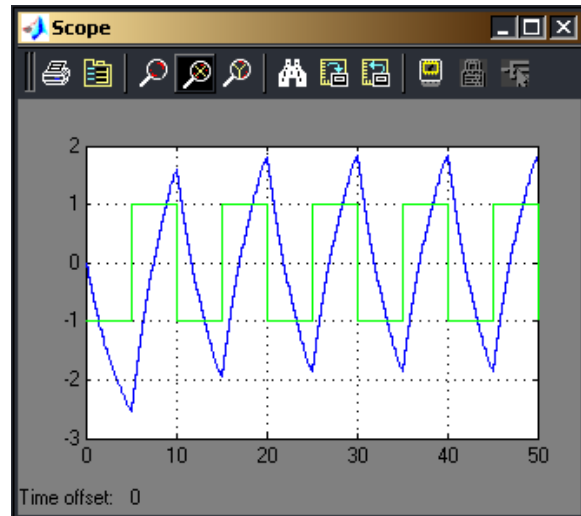
Sinus-Eingang:



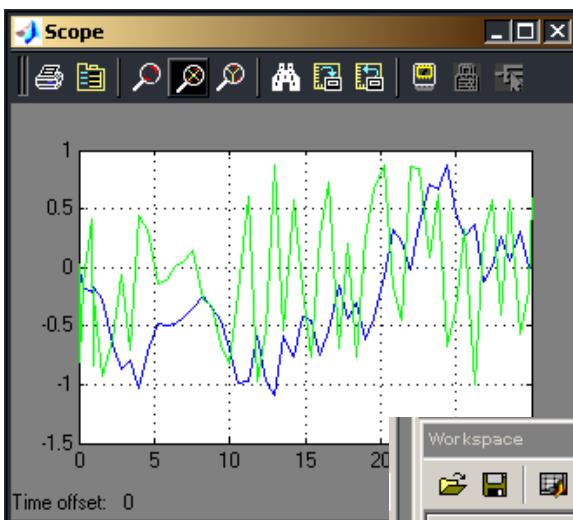
Sägezahn:



Rechteck:



Random:



Workspace

Name	Size
ScopeData	1x1
ans	58x2
simout	1x1
tempFixPtSimRan	0x0
tout	58x1

Command History

```
clear
ScopeData.Signals
ScopeData.signals
ScopeData.signals.values
```

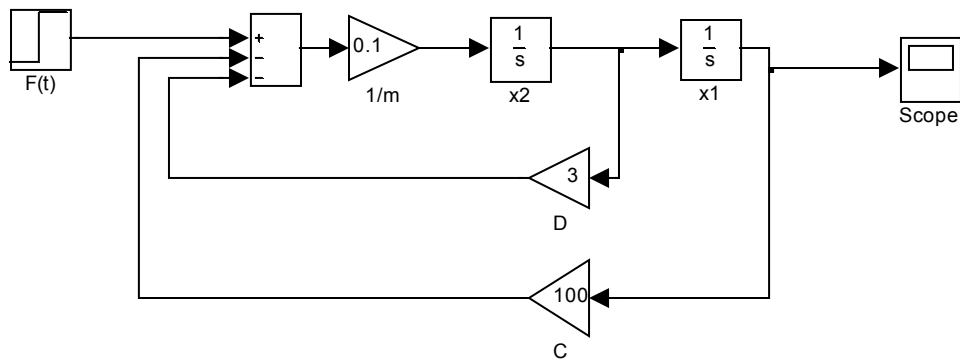
Command Window

```
>> ScopeData.signals.values
ans =
    0    0.0258
    0.0000   -0.0790
   -0.0006   -0.2992
```

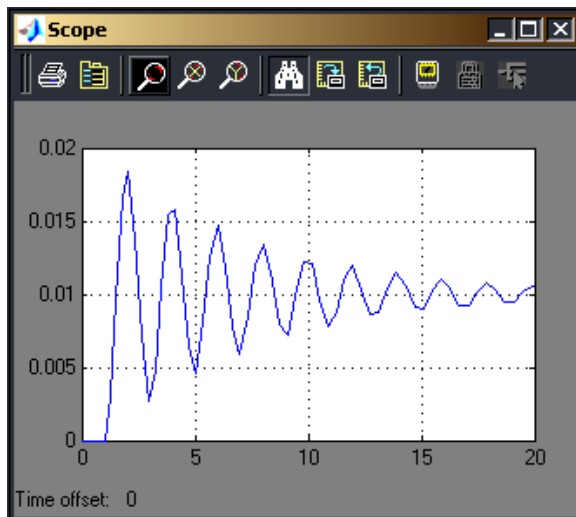
Array Editor: ScopeData

```
time: [58x1 double]
signals: [1x1 struct]
blockName: 'versuch3/Scope'
```

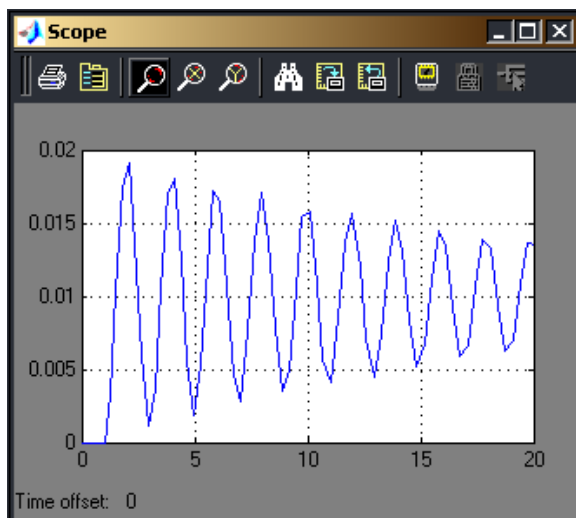
c) **Feder-Masse-Schwinger**



Sprungantwort :



$F=1\text{ N}$   
 $C=100\text{ N/m}$   
 $D=3\text{ N}\cdot\text{sec/m}$   
 $m=10\text{ Kg}$



$F=1\text{ N}$   
 $C=100\text{ N/m}$   
 $D=1\text{ N}\cdot\text{sec/m}$   
 $m=10\text{ Kg}$

- Je kleiner die Dämpfung je länger die Schwingung,...
- Je größer die Federsteife je kleiner die Auslenkung bei gleicher Kraft,...
- Je größer die Masse je langsamer die Schwingung,...